

12th IGORR - October 28-30, 2009, CIAE-BEIJING, P.R. CHINA

Underwater NDE Systems in the JHR Towards integration issues



Underwater NDE Systems in the JHR: Required Systems

Two Imaging Systems (IS) in the reactor pool:

1 GXIS: Gamma & X Imaging System

Spectrometry passive y and Transmission High Energy X rays

⇒ Mechanical bench + collimator with a complex and accurate instrumentation architecture

Note: CEA and VTT (Finland) develop a collaboration to design and supply this GXIS system

- 1 NIS: Neutron Imaging System
 - => Using high neutron flux coming from the core
 - => Mechanical bench + underwater neutron collimation and instrumentation

JHR experimental programme objectives:

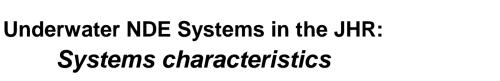
Assessment of irradiation nuclear fuel experiments

Emission and Transmission Nuclear Measurements + Tomography y and n

Interest:

Both systems may deliver Experimental results Images up to 3D (scanning, localised, tomography)

Complementarity between **n** and *y* assessments





Technical Objectives:

Higher accurate goals than present possibilities (OSIRIS, etc...)

Taking « realist to day state of art »:

Expected resolution of (100µm)³

 $=> to day ~(500 \mu m)^3$

Global Engineering Difficulties & Goals: Constraint interfaces (objective of this presentation)

Integration of accurate mechanical benches in the pool,

Design of the collimator plug penetration (feedthoughs with vessel liner and concrete frame, ...)

Main accurate exigences for the 3 axis & rotation positions:

X, Y, Z: +/- 0,1 mm

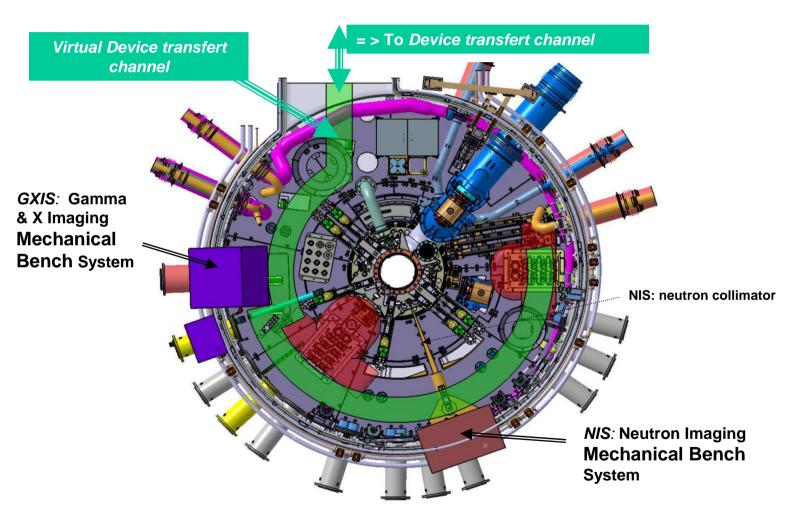
θ: +/- 0,05°

Specific assessment files: Safety, transfert exigencies, etc...

=> Especially: need of seismic mechanical design

Reactor Pool General Horizontal View: GXIS and NIS positions





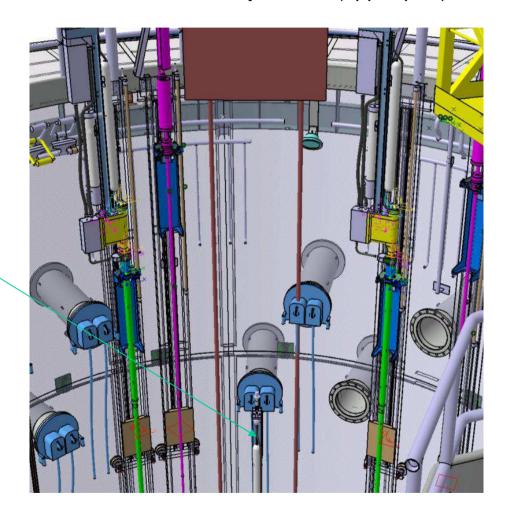
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NIS position (upper part)

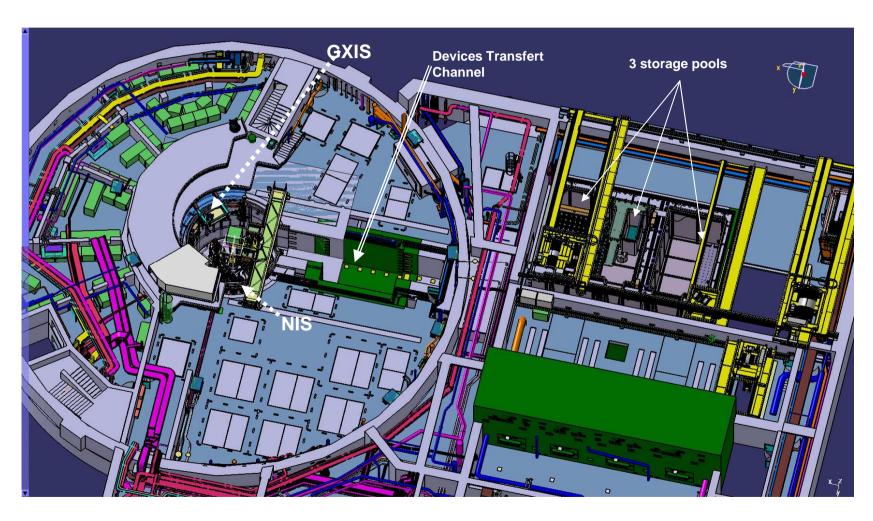


Head of experimental device settle settle on the neutron bench





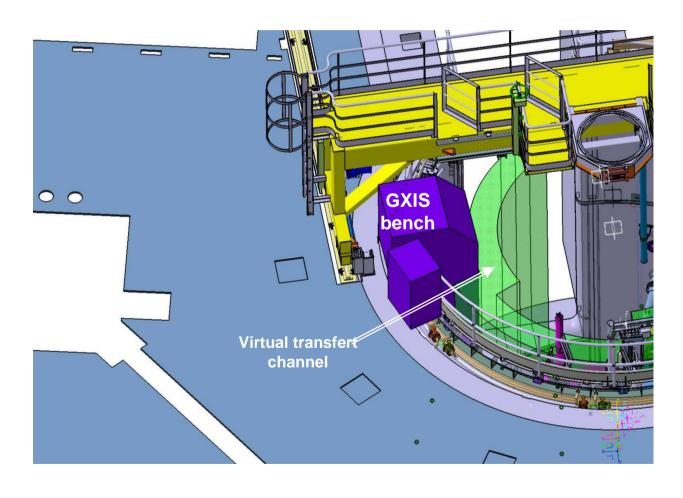
JHR General Horizontal View: Reactor and auxilliary zones







Interfaces with GXIS





NDE Systems in the JHR: GXIS system Development and management Expected Planning

=> CEA and VTT (Finland) develop a collaboration to design and supply this GXIS system

4 technical phases:

Feasibility: 2008 to ~june 2010

Conception (detail design) ~june 2010 to ~june 2011

Realization (and supply) ~june 2011 to end 2012

Installation (and tests on site JHR)
 2013 to ~june 2014



NDE Systems in the JHR: GXIS main interfaces difficulties

Close to the end of the feasability phase tree main technical challenges are noted:

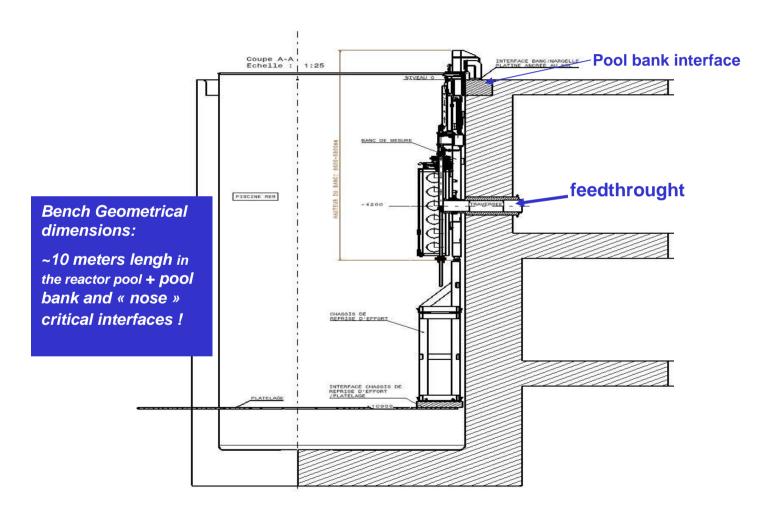
1. Mechanical accurancy: especially bench position

goal = 0.1 mm (compared to the bench lengh ~10 meters!)

- 1. Feedthrought (especially the « nose » guide which create a pool penetration): => critical interface « Bench / Pool Liner »
 - ⇒ leak risk to be excluded (the nose is a 2nd barrier): risk of internal agression to be excluded during working phases; need a deep analysis of seismic behavior
- 2. Mechanical behavior of the bench during a seismic scene
 - ⇒ Non agression of the liner
 - ⇒ integrity criteria (risk of internal agression to be excluded ..)
 - ⇒ High level of the set of acceleration references (despite of anti seismic technical dispositions)



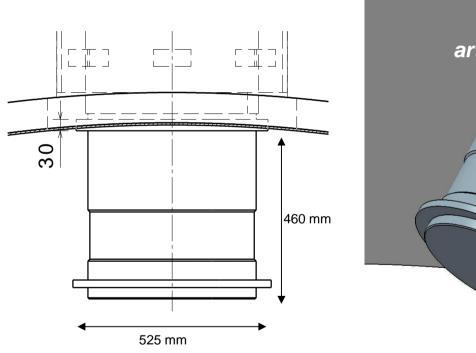
NDE Systems in the JHR Mechanical reactor bench: vertical view

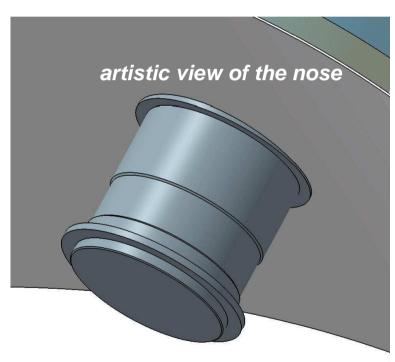




NDE Systems in the JHR Mechanical feedthrought

and « nose » interface with the bench

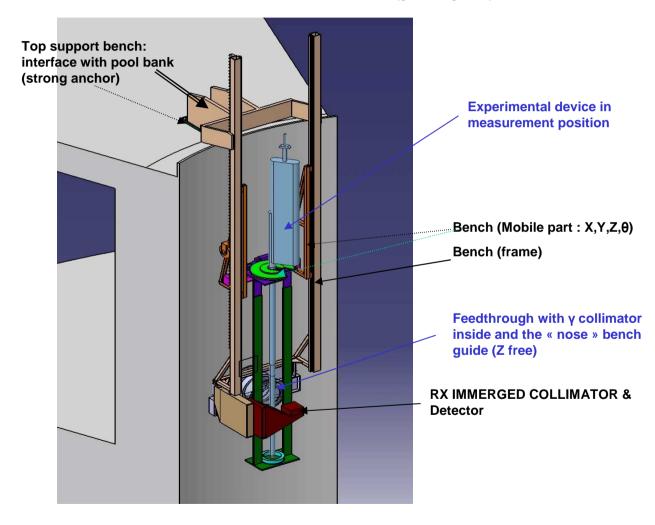




NDE Systems in the JHR: Gamma & X

Imaging System Mechanical Immerged Bench (principles)

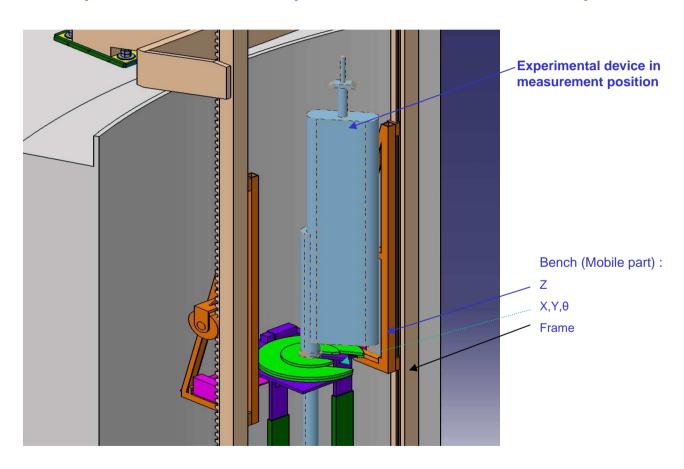








Principle View about « fuel experimental device/Bench mobile part »



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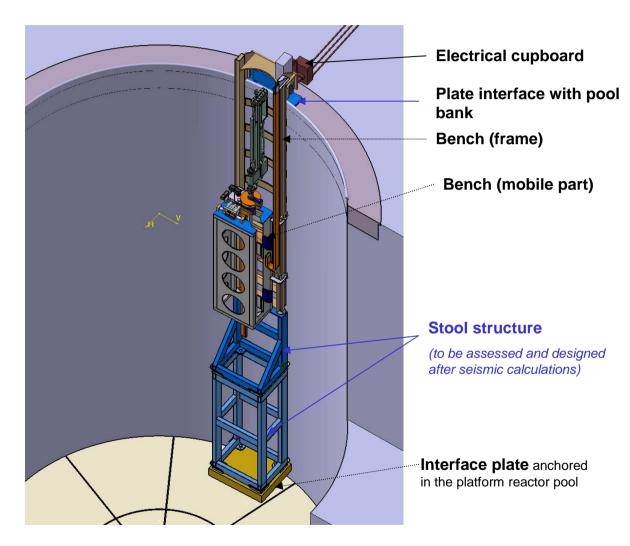
NDE Systems in the JHR:

Gamma & X Imaging System

Mechanical Bench Architecture: global

assembly (principles)





NDE Systems in the JHR Specific bench modular conception exigences



